

Application Note:

Closed Loop Control System

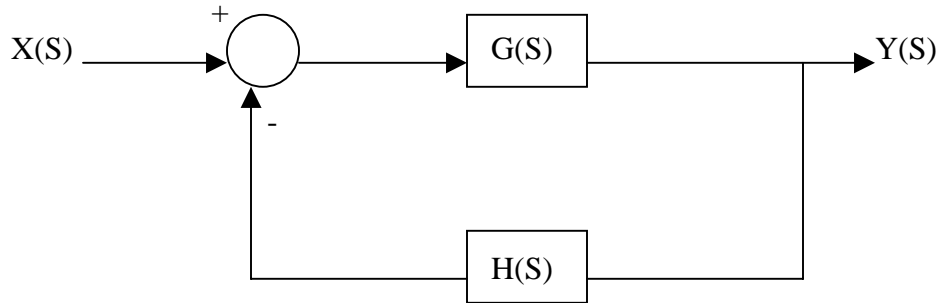
Contact:

Brazen Tek
20121 Ventura Blvd.
Suite 310
Woodland Hills, CA 91364
Tel/Fax: (818) 710-9262
E-mail: info@brazentek.com

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Review



Note: X(S): Input function
G(S): Controller function
Y(S): Output function
H(S): Transfer Function (feedback)

Output is obtained by:

$$Y(S) = \frac{G(S) X(S)}{1 + G(S) H(S)}$$

Y(S) is also denoted as feedback transfer function.

The question is why closed loop?

The simple answer to this is because we have control over the behavior of the system by adding a feedback.

How much control can we have?

This depends on the type of system performance is desired. Better performance requires better feedback.

Other important factor about closed loop control system is that it provides a stable performance when dealing with the system feedback. This is where in some applications, PLL (Phase lock loop) is deployed where closed loop bandwidth is often referred to as PLL bandwidth.



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